



Response reduction using anti-resonance point of seismic isolation device with inertial mass damper

Yousuke Sakai, Nanako Miura, Keita Aoshima and Akira Sone

EasyChair preprints are intended for rapid dissemination of research results and are integrated with the rest of EasyChair.

June 26, 2019

Response reduction using anti-resonance point of seismic isolation device with inertial mass damper

Yousuke Sakai¹, Nanako Miura¹, Keita Aoshima¹, and Akira Sone¹

¹Kyoto Institute of Technology, Matusgasaki, Sakyo-ku, Kyoto, 606-8585, Japan
(yousukeghi@gmail.com)

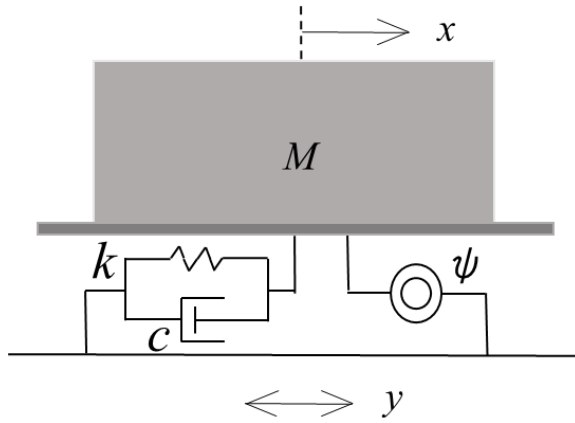
Keywords: Anti-resonance, Inertial mass damper, Seismic isolation device, Seismic response

In recent years, active seismic isolation devices have been developed. However, they do not operate when the external power supply is shut off. To solve this problem, a self-powered active seismic isolation device based on the idea of electric power regeneration has been proposed (K. Nakano et al., 2002). This device can control using regenerated vibration energy from seismic motion, and doesn't need external energy to produce control force. However, when long-period earthquake occurs, this device can't regenerate enough electric power to decrease the vibration response. So we propose a new model using a rotating inertial mass damper (inertor) which can decrease vibration and regenerate electric power more effectively than the previous model. An inertor is a device that rotates a weight and can obtain a larger inertial mass than the actual mass. Using power regeneration, a device has been proposed that incorporates a motor in the inertor, and the power regeneration effect is shown by numerical simulation (K. Aoshima et al., 2018).

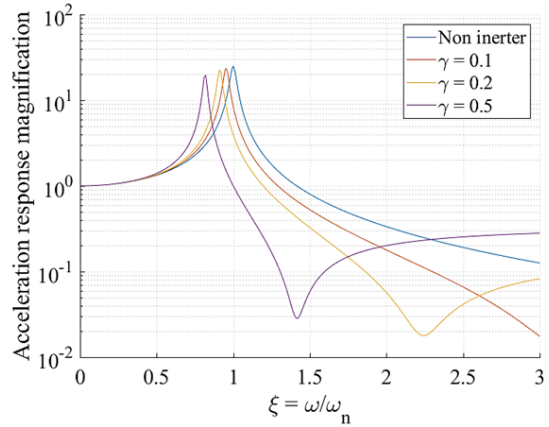
Focusing on the response characteristics in the frequency domain of this model, it is known that there is an anti-resonance point where the response drops significantly. The anti-resonance point changes the degree of response reduction and the value with respect to the frequency when the structural parameters change.

In this research, we indicated the characteristics of the anti-resonance point by differentiating the frequency response curve. And we confirmed that how the structural parameters affect the anti-resonance point by simulation. Moreover, we propose a new design of the device based on an anti-resonance.

Figure 1 shows a seismic isolation model using an inertor, where ψ is the inertor, and γ in Fig.1(b) is the mass ratio of the inertia mass to the mass M . Fig.1(b) shows that when the γ changes, the anti-resonance point changes in the frequency domain. Thus, the position of the anti-resonance point can be changed by installing some elements to the device.



(a) Analysis model



(b) Acceleration response magnification

Fig.1 Basic model

Figure 2 shows the seismic isolation model with more elements, where the red symbols are set as variable parameters. We differentiated the acceleration response magnification of this model, and we indicated the characteristics of the anti-resonance point.

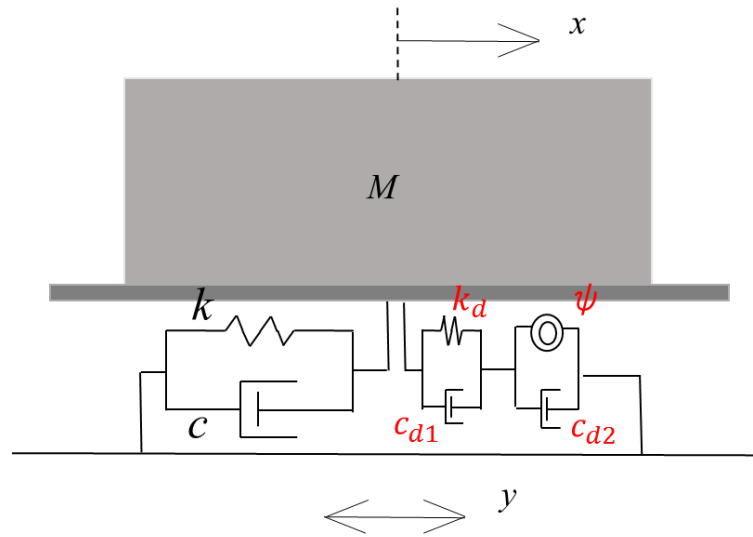


Fig.2 Hybrid model

Reference

K. Nakano, Y. Suda, and S. Nakadai, "Realization of Self-Powered Active Control Systems on the Basis of Energy Balance Analysis", Transactions of the Japan Society of Mechanical Engineers, Series C, Vol.68, No.666, pp.64-70, 2002.(in Japanese)
 K. Aoshima, N. Miura, and A. Sone, "A Study of Self-powered Active Seismic Isolation Floor Device Using Rotational Inertia Mass Damper", ASME 2018 Pressure Vessels and Piping Conference Paper No.84354, 2018.